

rotork®

Process Controls

CVQ Series

QuickStart Guide



Quarter-turn Control Valve Actuator

Established Leaders in Actuation Technology

Introduction

This QuickStart Guide covers the Quarter-Turn control valve actuator range (CVQ).

Models: CVQ 1200 & CVQ 2400

Refer to Rotork PUB042-001-00 for full specification.

Building on Rotork's historical success with innovative technology, the CVQ offers a highly accurate and responsive method of automating control valves without the complexity and cost of a pneumatic supply. With an increased focus on production costs and efficiency, accurate control of the process variable is paramount.

With resolution figures better than 0.1% and the ability to eliminate position overshoot, the Rotork CVA range helps to maximize product quality and plant capacity.

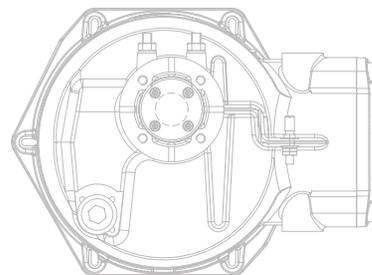
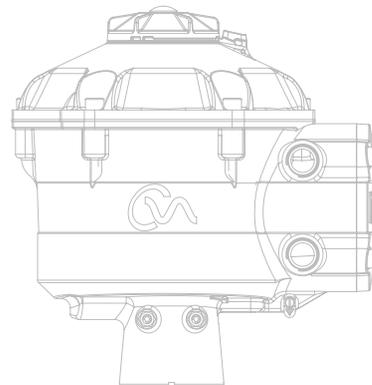
CVA range actuators are self contained, purpose designed and built for continuous remote electrical operation of control valves.

The actuator comprises:

- DC brushless electric motor.
- Reduction gearing with quadrant output gear.
- Motor controller with speed, travel and torque limitation.
- Electronic logic controls and monitoring facilities housed in a double sealed watertight enclosure.
- Hazardous area certification meeting international and national requirements.

All torque and position settings as well as configuration of the actuator are made using a non-intrusive Bluetooth device, typically a PDA (not supplied).

Bluetooth™ PDA software is available for free download from www.rotork.com.



Installation & Setup Guide

Commissioning

Move the actuator selector knob to the 'STOP' position.

Apply Electrical Power

On completion of the correct assembly and electrical connection procedures, the electrical power supply can now be applied to the actuator.

NOTE: If the unit is fitted with failsafe capacitors the Green or Red LED (depending on Mode selected) on the selector will flash until the capacitors are fully charged.

Movement is not possible whilst the LED is flashing.



Fig. 3.1

Establish Bluetooth™ Communications

It is now required to establish communications in order to complete the fitting procedure.

Ensure Bluetooth is enabled on the PDA then click on the Enlight Icon to start the program.

The maximum range of Bluetooth communication is 10 Meters.

The first screen gives the option to connect to an actuator or open a saved file.



Fig. 3.2

WORK OFF LINE

If there is a configuration file stored in the PDA it can be opened to review files.

RECONNECT AN ACTUATOR

If a link between the PDA and actuator has previously been established a list will appear and a search for new devices will not occur.

DISCOVER A NEW ACTUATOR

The PDA will search a radius of 10 meters for CVA actuators.

QUIT

Exit the menu.

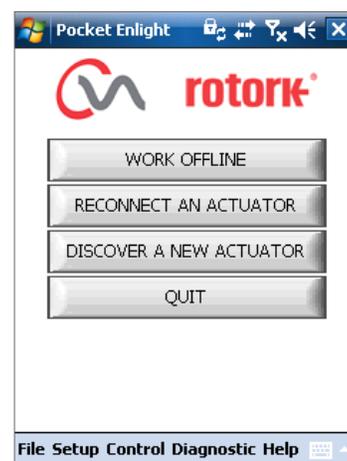


Fig. 3.3

Installation & Setup Guide

Reconnect or discover an actuator

Searching for Actuator

The PDA will now search for any CVA actuators within Bluetooth range.

If there is more than one device a list will be generated.

Highlight, then select the required actuator from the list of units within range.

The actuator will generally report its identity by its serial number (shown on nameplate).

This can be modified to add an MOV or Tag reference. (See full PDA menu details)

If there are numerous Bluetooth devices in range the search process will take longer to complete and in some cases may have to be repeated.

Login procedure

Before the link can be established it is necessary to log in.

There are three levels of login with password protection to limit higher level access.

View

Allows review of actuator settings only. No changes can be made.

Password : **view**

User

Allows access to review and change actuator settings. Includes the facility to set limits of travel and take local control of the actuator.

Default Password : **sulis**

This password can be changed using the 'Setup' menu to provide additional site security.

DO NOT LOSE THE PASSWORD INFORMATION

Rotork Engineer

Rotork use only.

Login

Select '**User**' on the User Level drop down menu. Note, user is the default and will appear in the box.

Using the keyboard at the bottom of the screen, type in the password then click on 'OK' to start the procedure. If communication is successful you will be prompted to wait whilst the setup data is retrieved from the actuator.

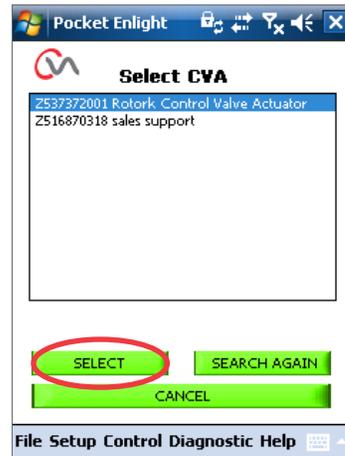


Fig. 4.1

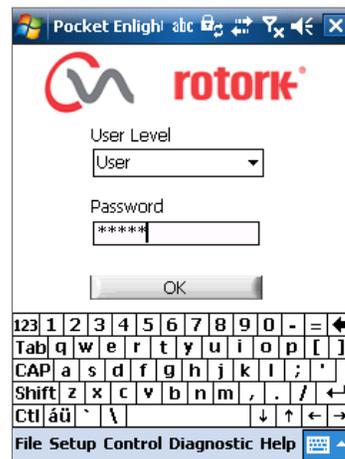


Fig. 4.2



Fig. 4.3

Installation & Setup Guide

If the incorrect password is entered an error message will be displayed. The actuator password cannot be reset. An error code will be generated, make a note of the code then please contact your local Rotork representative stating the full error code.

The actuator's current password may then be verified and confirmed.

Stroke Setup Menu

There are three choices from this menu.

Align Coupling

If the actuator is not fully fitted to the valve this procedure must be carried out to enable alignment of the actuator coupling and adjustment of Stop Bolts.

Quick Setup Wizard

Use this menu to automatically set actuator limits of travel.

Go to Page 11

Manual Setup

Use this menu to manually set actuator limits of travel.

See publication PUB042-004 for further details.

It is possible on this screen to choose Imperial or Metric units. The actuator serial number, current valve stroke and position are also displayed.

WARNING

The default setting of a new actuator is **minimum torque and clockwise to close**. If the actuator has previously been commissioned it is essential that its basic settings be checked before fitting the coupling and operating the actuator electrically. Check the settings in the Manual Setup menu, adjust if necessary.

WARNING

When RUN mode is selected the actuator will respond to any active remote control commands.

Select 'STOP' on the Actuator Selector Knob to prevent any unwanted movement.

Fitting Actuator to Valve

Select the **'ALIGN COUPLING'** option.
Select Metric or Imperial Units as required.

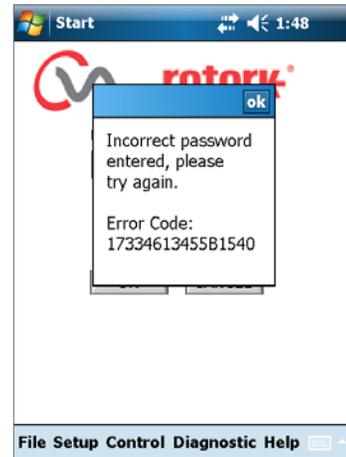


Fig. 5.1

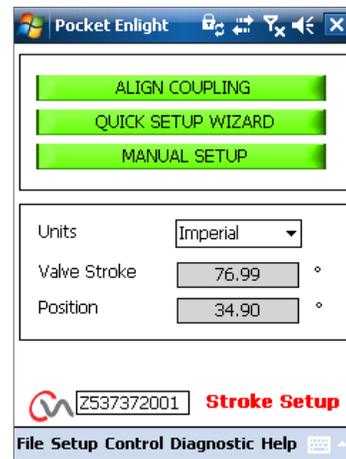


Fig. 5.2

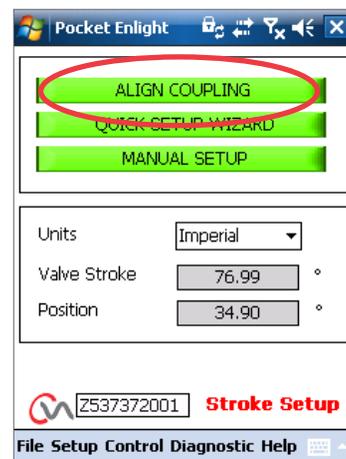


Fig. 5.3

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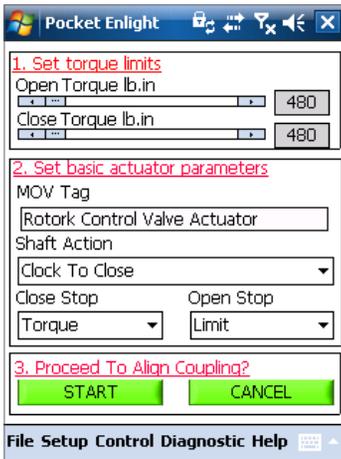


Fig. 6.1

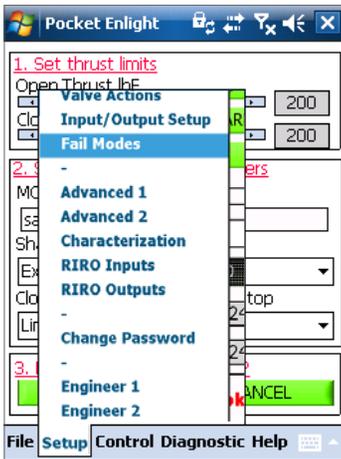


Fig. 6.2

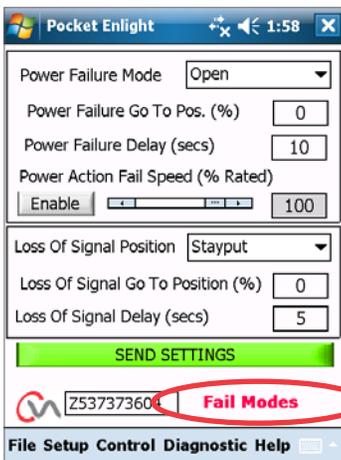


Fig. 6.3

1. Set torque limits

The maximum amount of torque available for the open and close direction of travel can be adjusted by dragging the slider from left to right.

2. Set basic actuator parameters

MOV Tag

The actuator can be given a TAG number for ease of identification in the field.

Shaft Action

Set Clock or Anticlock direction to close the output drive shaft.

Close/Open Stop

Torque - Apply set torque to the valve stem at end of travel limit where valve tight shutoff is required.

Limit - Stop the actuator at the set limit where valve does not require tight shutoff.

Select the START option to save changes.

Select basic parameters and torque limit settings as required.

3. Proceed To Align Coupling

To commence manual alignment of coupling and adjustment of Stop Bolts, click on the start box.

⚠ WARNING

When RUN mode is selected the actuator will respond to any active remote control commands.

If no Analogue request is applied the actuator will carry out its loss of control signal fail to position function. If necessary go to the Fail Modes Menu and select the STAYPUT option and send the settings back to the actuator.

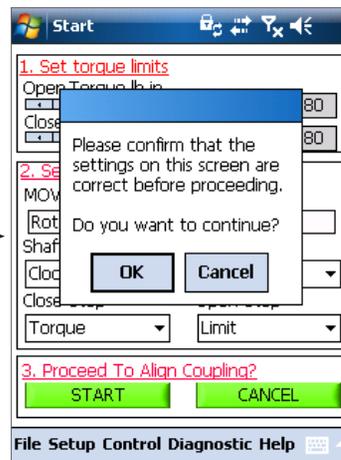


Fig. 6.4

Installation & Setup Guide

Align Coupling - Adjust Stop Bolts

It is now possible to operate the actuator using the Enlight program.

Moving the position control slider will rotate the output shaft to enable alignment of the drive bush to the valve stem and adjustment of the STOP bolts. Coarse control will allow full travel of the actuator. Fine control is used for small adjustments of the actuator Output shaft.

Incrementing the position slider using the arrows will vary position by 1% for coarse and 0.1% for fine control.

When the position control is operated for the first time a warning will appear to indicate that the actuator will be taken offline and will not respond to remote control commands.

⚠ CAUTION

The actuator will move to the indicated position on the Position Control Slider.

Select OK

Click on the 'OK' button, the actuator will be taken offline and will now move to the position as indicated on the position control slider.

The actuator is now unavailable for remote control.

Adjust Actuator Stop Bolts

Refer to the stop bolt adjustment procedure. Use the Fine and Coarse position slider to position the actuator during the stop bolt adjustment procedure.

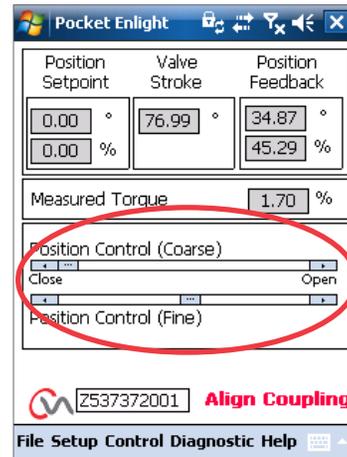


Fig. 7.1



Installation & Setup Guide

Stop Bolt Adjustment

It is recommended that stop bolt adjustment be carried out by the valvemaker/supplier before the valve is fitted on to the pipework.

Once installed the valvemaker/supplier should be consulted before stop bolt re-adjustment is carried out. After setting or adjustment of stop bolts the actuator limits must be reset.

The CVQ stop bolts are located below the main body assembly. The stop bolt adjustment allows +/- 5% variation of travel at each end position. Screwing bolts in reduces the range of movement, out increases range of movement.

For clockwise closing valves the right hand bolt is the closed stop as shown in Fig 25.1. The left hand bolt is the open stop.

Stop bolts are factory set to give a nominal travel of 90 degrees.

Adjustment for non seating valve types

For closed and open stop position adjustment.

Undo stop bolt locknut. Move actuator and valve to the required stopping position (it may be necessary to unscrew stop bolt to allow more travel). Screw stop bolt in until a stop is felt. Tighten stop bolt lock nut.

Adjustment for seating valve types

Undo stop bolt locknut. Move actuator and valve to the required stopping position (it may be necessary to unscrew stop bolt to allow more travel).

Screw stop bolt in until a stop is felt and then back off by 1 to 3 turns.

Tighten stop bolt lock nut.

Set Actuator Limits of Travel

It is possible to set the limits manually if full valve stroke is not required or automatically using the Quicksetup wizard if full travel is required between the stop bolt positions.

Go to Page 11 for Quicksetup or see publication PUB042-004 for Manual setup options.

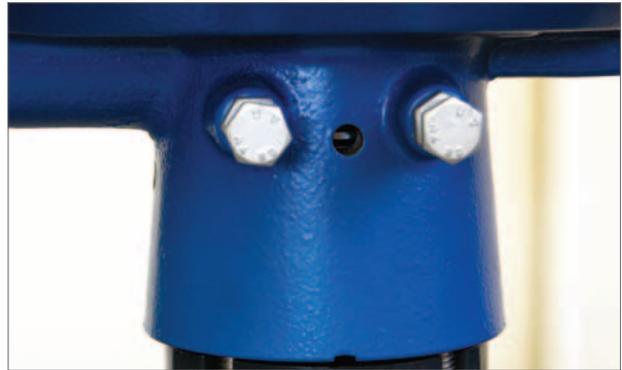


Fig. 8.1



Fig. 8.2



Fig. 8.3



Fig. 8.4

Installation & Setup Guide

Quick Setup Wizard

If the valve is to be commissioned over its full stroke the quick setup wizard is a fast and efficient way to set the end of travel limits.

The quick set up wizard will allow the actuator to find the end of travel by measuring the output torque.

If the valve is not required to operate over full stroke it is possible to set a fixed OPEN limit.

Select Quick Setup Wizard.

Set torque limits

The default torque values for the Auto setup are automatically set to 40% of rated torque in both directions. Adjust if more torque is required to move the valve through stroke.

Set basic actuator parameters

The MOV tag can be edited. Use the keyboard to edit the MOV tag field.

Shaft Action

Select direction to close the output shaft to suit valve operation.

Close / Open Stop

Set the end of travel stop function for Torque or Limit to suit the characteristics of the valve.

Torque

The actuator can be set to apply its selected output 'Torque' to the valve at the end of travel where tight shut off is required.

Limit

Alternatively it can be set to the 'Limit' function to disengage motor drive and stop the valve at a predetermined position where the valve does not require the seating force to be applied to the valve seat or end of mechanical valve travel.

Click on the 'START' box to save changes to the actuator and initiate the Auto Setup routine.

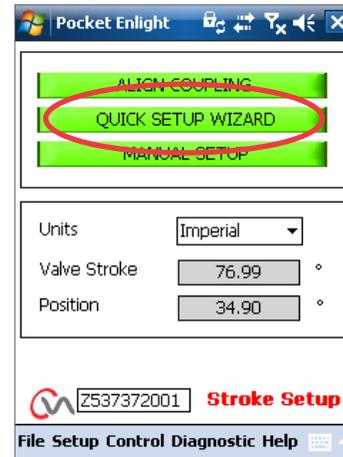


Fig. 9.1

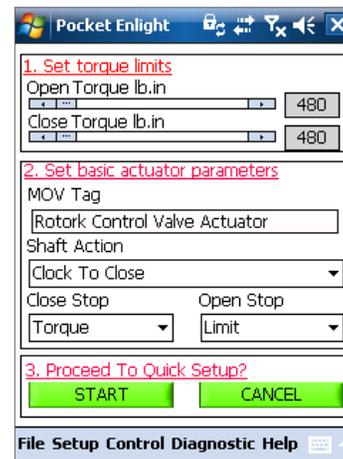


Fig. 9.2

Installation & Setup Guide

Move the selector Knob to the 'RUN' position



CAUTION

Initiating an Auto Limit will move the valve through its full stroke.

WARNING

Ensure torque, shaft action and end stops are correctly set or damage to the valve may occur.

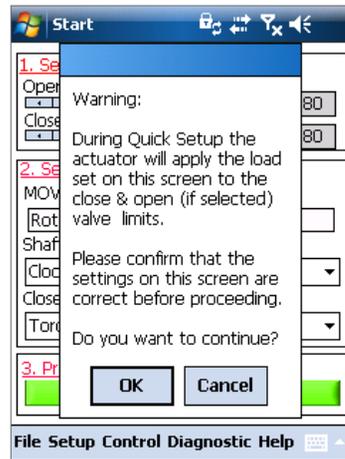


Fig. 10.1

AUTO LIMIT will initiate the auto setting procedure

FIXED LIMIT will allow the actuator to find the closed limit by measuring the torque but will allow the open limit to be set at a measured distance. The distance can be edited in the text box.

NOTE: Ensure that limit is selected for the open stop if fixed limit is applied.

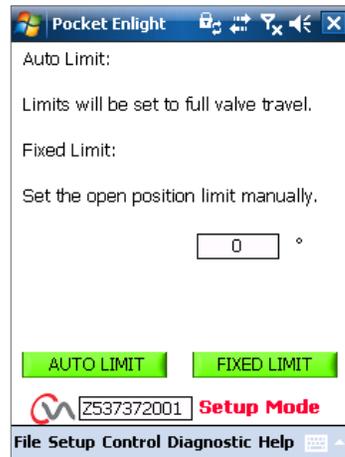


Fig. 10.2

Installation & Setup Guide

The Quick Setup is fully automatic and requires no user input

Start Quick Setup?

Click on the 'START' box to initiate the Quick Setup procedure. Click on the OK box to continue. All other menus will be disabled until the process is completed.

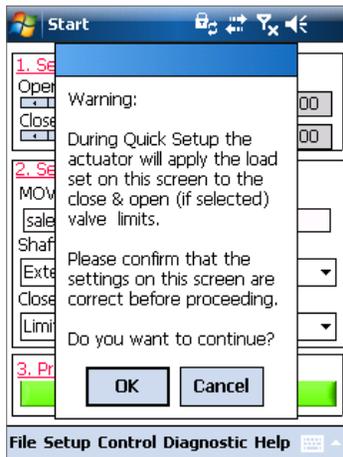


Fig. 11.1

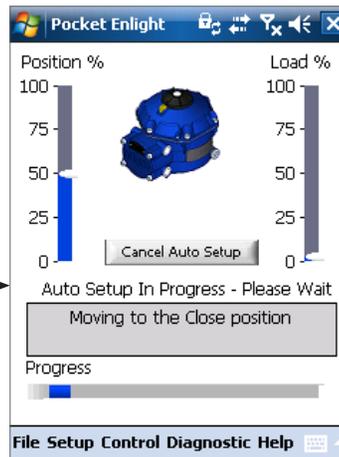


Fig. 11.2

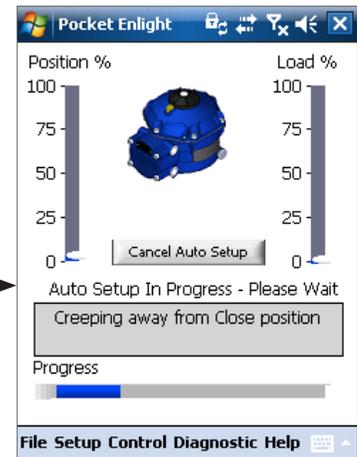


Fig. 11.3

Finding the Closed Limit

The actuator will turn its output shaft to the maximum CLOSED limit of travel.

Actuator will then turn its output shaft away from the Closed limit of travel and repeat the procedure to eliminate any inertia effects and re-adjust the end of travel limit as necessary.

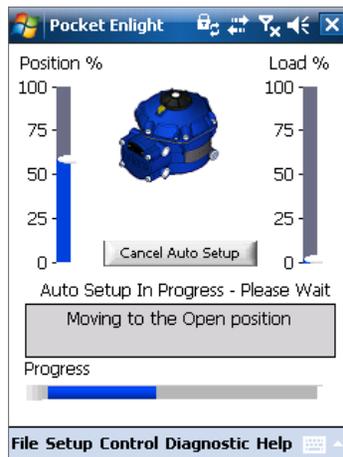


Fig. 11.4

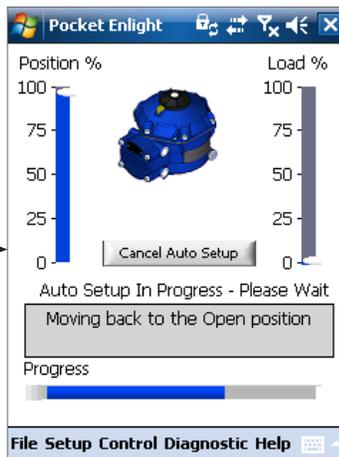


Fig. 11.5

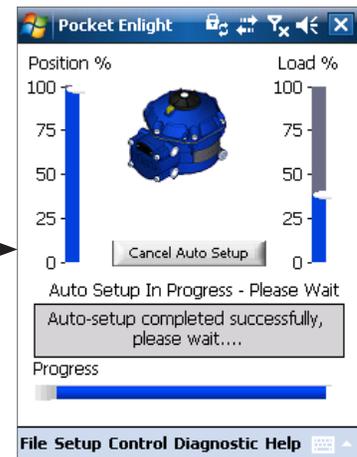


Fig. 11.6

Finding the Open Limit

The actuator will turn its output shaft to the maximum Open limit of travel. Actuator will then turn its output shaft away from the Open limit of travel and repeat the procedure to eliminate any inertia effects and re-adjust the end of travel limit as necessary.

The Open position limit is now set and Auto Setup is Complete.

Installation & Setup Guide

REFERENCE STROKE

On completion of the Quick setup action a prompt to record a new torque reference stroke screen appears.

Select 'CANCEL' to finish Quick setup without recording a new torque profile.

Select 'OK' to record a new Torque Profile.

This function will clear the datalogger torque profile logs. The actuator will carry out an Open and a Closed operation. A new torque profile will be generated for the Open and Close directions and can be accessed on future downloads.

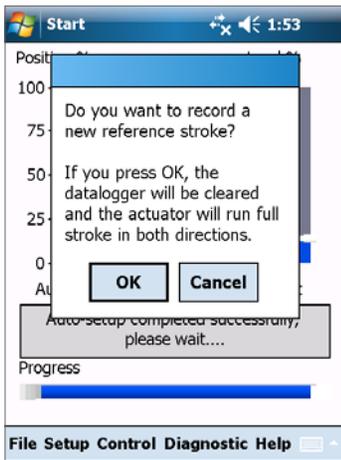


Fig. 12.1

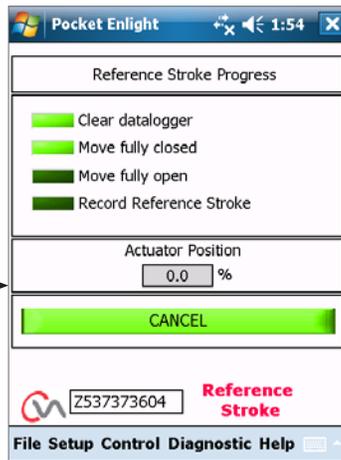


Fig. 12.2

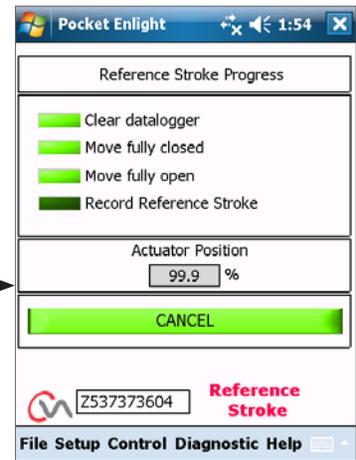


Fig. 12.3

ACTUATOR AUTOMATIC SETUP IS NOW COMPLETE

Auto setup is now complete and both ends of travel tight shut off limits have been defined and set.

PDA screen will return to the Stroke Set up menu.

If no further settings are required move the Mode selector to the 'STOP' or 'RUN' positions depending on desired Operation.

Exit the menu.

For further settings see publication PUB042-004.

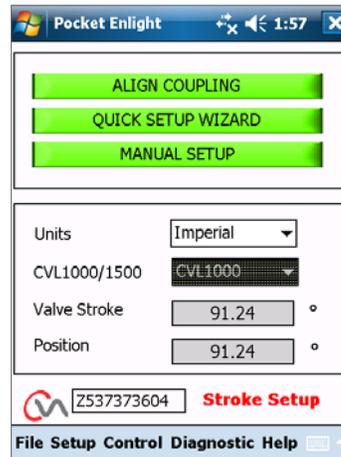
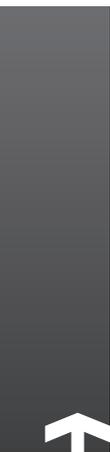


Fig. 12.4

Notes



Notes



Notes



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rotork® Process Controls

UK

Rotork plc
tel +44 (0)1225 733200
fax +44 (0)1225 333467
email mail@rotork.com

USA

Rotork Process Controls
tel +1 (414) 461 9200
fax +1 (414) 461 1024
email rpcinfo@rotork.com



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